

Preface

“Discrete Convex Analysis” is aimed at establishing a novel theoretical framework for solvable discrete optimization problems by means of a combination of the ideas in continuous optimization and combinatorial optimization. The theoretical framework of convex analysis is adapted to discrete settings and the mathematical results in matroid/submodular function theory are generalized. Viewed from the continuous side, the theory can be classified as a theory of convex functions $f : \mathbf{R}^n \rightarrow \mathbf{R}$ that have additional combinatorial properties. Viewed from the discrete side, it is a theory of discrete functions $f : \mathbf{Z}^n \rightarrow \mathbf{Z}$ that enjoy certain nice properties comparable to convexity. Symbolically,

Discrete Convex Analysis = Convex Analysis + Matroid Theory.

The theory puts emphasis on duality and conjugacy as well as on algorithms. This results in a novel duality framework for nonlinear integer programming.

Two convexity concepts, called L-convexity and M-convexity, play primary roles, where “L” stands for “Lattice” and “M” for “Matroid.” L-convex functions and M-convex functions are convex functions with additional combinatorial properties distinguished by “L” and “M,” and they are conjugate to each other through a discrete version of the Legendre–Fenchel transformation. L-convex functions and M-convex functions generalize, respectively, the concepts of submodular set functions and base polyhedra of (poly)matroids.

L-convexity and M-convexity prevail in discrete systems.

- In network flow problems, flow and tension are dual objects. Roughly speaking, flow corresponds to M-convexity and tension to L-convexity.
- In matroids, the rank function corresponds to L-convexity and the base family to M-convexity.
- M-matrices in matrix theory correspond to L-convexity, and their inverses to M-convexity. Hence, in a discretization of the Poisson problem of partial differential equations, for example, the differential operator corresponds to L-convexity and the Green function to M-convexity.
- Dirichlet forms in probability theory are essentially the same as quadratic L-convex functions.

The present book is intended to be read profitably by graduate students in operations research, mathematics, and computer science, and also by mathematics-

oriented practitioners and application-oriented mathematicians. Self-contained presentation is envisaged. In particular, no familiarity with matroid theory nor with convex analysis is assumed. On the contrary, the reader will hopefully acquire a unified view on matroids and convex functions through a variety of examples of discrete systems and the axiomatic approach presented in this book.

I would like to express my appreciation for encouragement, support, help, and criticism that I have received during my research on the theory of “Discrete Convex Analysis.” Joint works with Akiyoshi Shioura and Akihisa Tamura have been most substantial, and collaborations with Satoru Fujishige, Satoru Iwata, Gleb Koshevoy, and Satoko Moriguchi enjoyable. Moral support offered by Bill Cunningham, András Frank and Láci Lovász has been encouraging. I have benefited from discussions with and/or comments by Andreas Dress, Atsushi Kajii, Mamoru Kaneko, Takahiro Kawai, Takashi Kumagai, Tomomi Matsui, Makoto Matsumoto, Shiro Matuura, Tom McCormick, Yoichi Miyaoka, Kiyohito Nagano, Maurice Queyranne, András Recski, András Sebő, Maiko Shigeno, Masaaki Sugihara, Zoltan Szigeti, Takashi Takabatake, Yoichiro Takahashi, Tamaki Tanaka, Fabio Tardella, Levent Tunçel, Jens Vygen, Jun Wako, Walter Wenzel, Yoshitsugu Yamamoto, and Zaifu Yang. In preparing this book I have been supported by several friends. Among others, Akiyoshi Shioura and Akihisa Tamura went through the text and provided comments, and Satoru Iwata agreed that his unpublished results be included in this book. Significant part of this book is based on my previous book [147] in Japanese published from Kyoritsu Publishing Co. Finally, I express my deep gratitude to Peter Hammer, the chief editor of this monograph series, for his support in the realization of this book.

October 2002

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